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Supplementary Material for "The Effects of Foreign Exchange Intervention: Evidence from a

Rule-Based Policy in Colombia"

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# Supplementary Material for "The Effects of Foreign Exchange Intervention: Evidence from a Rule-Based Policy in Colombia"* 

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#### Abstract

This Appendix provides a more detailed discussion of the technical results, including proofs of theorems reported in the main paper. For ease of reference notation and definitions are repeated from the main paper.


Key Words: Rule-Based Foreign Exchange Interventions, Portfolio Balance, Central Bank Policy, Regression Discontinuity, Non-linear Impulse Response.

JEL Codes: E58, F31, C22

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## 1 Model and Assumptions

Let $\chi_{t}$ be a strictly stationary stochastic process defined on a probability space $(\Omega, \mathcal{F}, P)$ and taking values in $\mathbb{R}^{d}$. Let $\mathcal{F}_{l}^{k}=\sigma\left(\chi_{t}: l \leq t \leq k\right)$ be the sigma field generated by $\left\{\chi_{t}\right\}_{t=l}^{k}$. The strong mixing coefficient $\alpha_{m}$ is defined as

$$
\alpha_{m}=\sup _{A \in \mathcal{F}_{-\infty}^{0}, B \in \mathcal{F}_{m}^{\infty}}|P(A \cap B)-P(A) P(B)|
$$

The process $\chi_{t}$ is called strongly mixing (Doukhan, 1994) if $\alpha_{m} \rightarrow 0$ as $m \rightarrow \infty$.
Let $\left(y_{t}, X_{t}\right)$ be macroeconomic variables measurable with respect to $\mathcal{F}_{a}^{t}$ for some $-\infty<a \leq t$. If $\chi_{t}$ is strongly mixing then also ( $y_{t}, X_{t}$ ) are strongly mixing. We will refer to $y_{t}$ as the outcome variable and $X_{t}$ as the running variable. As in Hahn, Todd and Van der Klaauw (2001), consider the sharp regression discontinuity design where the policy $D_{t}$ is enacted if $X_{t}$ crosses a threshold $c$,

$$
D_{t}=1\left\{X_{t}>c\right\}
$$

The setup is flexible enough to include cases where $y_{t}=X_{t}$. This situation may occur when past realizations of the outcome variable are used to trigger the policy $D_{t}$. HTV demonstrate under what conditions a regression discontinuity design can be used to identify treatment effects in the potential outcomes framework of Rubin (1974). Here we show how to identify non-linear impulse response functions using regression discontinuity designs. Recall that the outcome variable $y_{t+j}$ can be represented as

$$
y_{t+j}=F_{t, j}\left(0, \chi_{t}\right)+\theta_{j}^{D}\left(\chi_{t}\right) D_{t} .
$$

Because $\chi_{t}$ is strictly stationary it follows that the marginal and conditional distributions of $F_{t, j}\left(0, \chi_{t}\right)$ and $\theta_{j}^{D}\left(\chi_{t}\right)$ depend only on the horizon $j$ but not on $t$. In order to define the treatment effect of interest we impose the following assumption which is similar to Assumption A1 in HTV.

Assumption 1 The expectations $E\left[F_{t, j}\left(0, \chi_{t}\right) \mid X_{t}=x\right]$ and $E\left[F_{t, j}\left(1, \chi_{t}\right) \mid X_{t}=x\right]$ exist and are continuous in $x$ at $c$ for all $j \geq 1$.

Assumption 1is stronger than Assumption A1 in HTV in the sense that we not only require continuity of the conditional mean of $F_{t, j}\left(0, \chi_{t}\right)$ but also of that of $F_{t, j}\left(1, \chi_{t}\right)$. On the other hand, we do not assume that $\theta_{j}^{D}\left(\chi_{t}\right)$ is a fixed constant.

The parameter of interest is the expectation of the impulse response $\theta_{j}^{D}\left(\chi_{t}\right)$ conditional on $X_{t}=c$, given by

$$
\theta_{j}(c)=E\left[\theta_{j}^{D}\left(\chi_{t}\right) \mid X_{t}=c\right] .
$$

The parameter $\theta_{j}(c)$ is well defined by Assumption 1 and can be estimated by local linear regression (LLR) as advocated in HTV. LLR goes back to Fan (1992) and was studied in the context of regression discontinuity designs in HTV and Porter (2003). Masry and Fan (1997) establish asymptotic properties as well as bandwidth selection rules for LLR with dependent data. HTV propose to estimate $\theta_{j}(c)$ with two separate LLR on the subsamples where $D_{t}=1$ and $D_{t}=0$.

As noted in the proof of Theorem 1 and 1' of Hahn, Todd and Van der Klaauw (1999) (henceforth HTV99), the asymptotic distribution for the combined estimator of $\theta_{j}(c)$ can be easily obtained in the case of cross-sectional samples because the subsamples where $D_{t}=0$ and $D_{t}=1$ are independent. This is clearly not the case in the context of time series data considered here. Imbens and Lemieux (2008) note that the combined method of HTV can be represented in a numerically equivalent regression using appropriate dummies and interaction terms. The advantage of their formulation in our context is that it automatically produces joint inference that accounts for the (temporal) dependence in our data. An additional complication that arises in our case is the fact that we are also interested in the joint distribution of estimators of all $\theta_{j}(c)$ for $j=0, \ldots, J$. Neither the RD design nor the inclusion of multiple outcomes does directly correspond to the model considered in Masry and Fan (1997). T The necessary extensions are given here. Thus, let $a=\left(a_{1}, \ldots, a_{J}\right)^{\prime}, b=\left(b_{1}, \ldots, b_{J}\right), \gamma=\left(\gamma_{1}, \ldots, \gamma_{J}\right)^{\prime}$ and $\theta=\left(\theta_{1}(c), \ldots, \theta_{J}(c)\right)^{\prime}$. Extending Imbens and Lemieux (2008) define the estimator $\hat{\theta}$ of the parameter $\theta$ as the solution to

$$
(\hat{a}, \hat{b}, \hat{\gamma}, \hat{\theta})=\underset{a, b, \gamma, \theta}{\arg \min } \sum_{j=1}^{J} \sum_{t=1}^{T-J}\left(y_{t+j}-a_{j}-b_{j}\left(X_{t}-c\right)-\theta_{j} D_{t}-\gamma_{j}\left(X_{t}-c\right) D_{t}\right)^{2} K\left(\frac{X_{t}-c}{h}\right)
$$

where $K() \geq$.0 is a kernel function and $h$ is a bandwidth parameter, both to be specified in more detail below. Let $\Pi=(a, b, \theta, \gamma)$, be a $J \times 4$ matrix of parameters, $Y_{t}=\left(y_{t+1}, \ldots, y_{t+J}\right)^{\prime}$ and $Z_{t}=$ $\left(1,\left(X_{t}-c\right), D_{t},\left(X_{t}-c\right) D_{t}\right)^{\prime}$. Now define the data-matrices $Y=\left(Y_{1}, \ldots Y_{T-J}\right)^{\prime}, Z=\left(Z_{1}, \ldots Z_{T-J}\right)^{\prime}$ and $W=\operatorname{diag}\left(K\left(\left(X_{1}-c\right) / h\right), \ldots, K\left(\left(X_{T-J}-c\right) / h\right)\right)$. Then,

$$
\operatorname{vec} \hat{\Pi}^{\prime}=\left(I_{J} \otimes\left(Z^{\prime} W Z\right)^{-1} Z^{\prime} W\right) \operatorname{vec} Y
$$

where $I_{J}$ is the $J \times J$ dimensional identity matrix. The expression for $\hat{\Pi}$ is formally the same as for weighted least squares in a system of seemingly unrelated regressions (SUR) and indicates in particular that $\hat{\theta}_{j}$ for a particular horizon $j$ can be obtained by an individual weighted least squares regression for that horizon with the weights given by the kernel function. However, for joint inference on $\theta$ the joint distribution of these estimators needs to be derived. The following assumptions correspond to assumptions made in Masry and Fan (1997).

Assumption 2 (i)Let $f(x)$ be the marginal distribution of $X_{t}$. Assume that $f(x)$ is continuous and bounded.
(ii) $\left|f_{l}(u, v)-f(u) f(v)\right| \leq M<\infty$ for all $l>0$ where $f_{l}(u, v)$ is the joint density of $X_{0}$ and $X_{l}$.
(iii) The process $\chi_{t}$ is strong mixing with $\sum_{m=1}^{\infty} m^{a} \alpha_{m}^{1-2 / \delta}<\infty$ for some $\delta>2$ and $a>1-2 / \delta$.
(iv) The kernel function $K($.$) is a bounded density function satisfying u^{4 \delta+2} K(u) \rightarrow 0$ as $|u| \rightarrow \infty$.

Assumption 3 (i) The kernel $K($.$) is bounded with bounded support [-1,1]$.
(ii) Assume that $f_{l}(u, v) \leq M_{1}$ and $E\left[y_{1}^{2}+y_{j}^{2} \mid X_{0}=u, X_{l}=v\right] \leq M_{2}<\infty$ for all $l$ and $u$, $v$ in a neighborhood of $c$.
(iii) Let $\Sigma(x)=\operatorname{Var}\left(Y_{t} \mid X_{t}=x\right)$ and assume that $\Sigma(x)$ is positive definite and bounded for all $x$. For $\delta>2$ as in Assumption 2, $E\left[\left|y_{1}\right|^{\delta} \mid X=u\right] \leq M_{3}<\infty$ for all $u$ in a neighborhood of $c$.
(iv) assume $h_{T} \rightarrow 0$ and $T h_{T} \rightarrow \infty$. (we often used the notation $h$ instead of $h_{T}$ ). Assume that there is a sequence $s_{T}>0$ such that $s_{T} \rightarrow \infty$ and $s_{T}=o\left(\left(T h_{T}\right)^{1 / 2}\right)$ such that $\left(T / h_{T}\right)^{1 / 2} \alpha_{s_{T}} \rightarrow 0$ as $T \rightarrow \infty$.

An additional set of technical assumptions specific to the $R D$ estimator are similar to assumptions made in HTV.

Assumption 4 Let $m_{j}(x)=E\left[y_{t+j} \mid X_{t}=x\right], m_{j}^{+}\left(x_{0}\right)=\lim _{x \rightarrow x_{0}^{+}} E\left[y_{t+j} \mid X_{t}=x\right]$ and

$$
m_{j}^{-}\left(x_{0}\right)=\lim _{x \rightarrow x_{0}^{-}} E\left[y_{t+j} \mid X_{t}=x\right]
$$

For $x>c$, assume that $m_{j}^{+}(x)$ is twice continuously differentiable with uniformly bounded derivatives $m_{j}^{\prime+}(x), m_{j}^{\prime \prime+}(x)$ on $(c, c+M]$. Similarly, for $x<c, m_{j}^{-}(x)$ is twice continuously differentiable with uniformly bounded derivatives $m_{j}^{\prime-}(x), m_{j}^{\prime \prime-}(x)$ on $(c-M, c)$ for some $M . \operatorname{Let} \Sigma^{+}\left(x_{0}\right)=\lim _{x \rightarrow x_{0}^{+}} \operatorname{Var}\left(Y_{t} \mid X_{t}=x\right)$, $\Sigma^{-}\left(x_{0}\right)=\lim _{x \rightarrow x_{0}^{-}} \operatorname{Var}\left(Y_{t} \mid X_{t}=x\right)$ and assume that $\Sigma^{+}\left(x_{0}\right), \Sigma^{-}\left(x_{0}\right)$ positive definite for $x_{0}=c$.

## 2 Results

This section summarizes the results for the identification of the impulse response function and the asymptotic distribution of vec $\hat{\Pi}^{\prime}$ and of individual components of this vector. In particular the joint distribution of the impulse response function $\theta$ as well as of individual components $\theta_{j}$ is of interest. The latter are useful for optimal bandwidth selection which leads to similar results as in Masry and Fan (1997) and Imbens and Kalyanaraman (2012).

We start with a result on the identification of the impulse response function.

Theorem 5 Assume that there is a non-random function $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$ of $\chi_{t}$ such that $g\left(\chi_{t}\right)=X_{t}$ and $c$ is a known threshold. Let $D_{t}=1\left\{X_{t}>c\right\}$. If Assumption 1 holds, it follows that

$$
\theta_{j}(c)=\lim _{x \rightarrow c^{+}} E\left[y_{t+j} \mid X_{t}=x\right]-\lim _{x \rightarrow c^{-}} E\left[y_{t+j} \mid X_{t}=x\right]
$$

Assume that there exists at least one continuous path $\varepsilon(\delta):[0, \infty) \rightarrow \mathbb{R}^{d}$ such that $g\left(\chi_{t}+\varepsilon(\delta)\right)-$ $g\left(\chi_{t}\right)=\delta$ for all $\delta \geq 0$ and $\varepsilon(0)=0$.Assume that $E\left[F_{t, j}\left(D_{t}, \chi_{t}\right) \mid \chi_{t}=x\right]$ is continuous in $x$ a.s., $\left|E\left[F_{t, j}\left(D_{t}, \chi_{t}\right) \mid \chi_{t}\right]\right| \leq B\left(\chi_{t}\right)$ and $E\left[B\left(\chi_{t}\right) \mid X_{t}=c\right]<\infty$ a.s. Let $\theta_{j}\left(\varepsilon, \chi_{t}\right)=F_{t, j}\left(D_{t}\left(\chi_{t}+\varepsilon\right), \chi_{t}+\varepsilon\right)-$ $F_{t, j}\left(D_{t}\left(\chi_{t}\right), \chi_{t}\right)$. Then it follows that

$$
\theta_{j}(c)=\lim _{\delta \downarrow 0} E\left[\theta_{j}\left(\varepsilon(\delta), \chi_{t}\right) \mid X_{t}=c\right]
$$

Remark 1 Note that the local conditional independence assumption used in HTV, Theorem 2 is not needed here because we only consider sharp regression discontinuity designs.

We introduce the following notation needed for the statements of the asymptotic distributions. Let $\mu_{l k}=\int_{-\infty}^{\infty} 1\{u>0\}^{k} u^{l} K(u) d u$ and define the matrix

$$
\Gamma=\left[\begin{array}{llll}
\mu_{00} & \mu_{10} & \mu_{01} & \mu_{11} \\
\mu_{10} & \mu_{20} & \mu_{11} & \mu_{21} \\
\mu_{01} & \mu_{11} & \mu_{01} & \mu_{11} \\
\mu_{11} & \mu_{21} & \mu_{11} & \mu_{21}
\end{array}\right]
$$

Let $v_{l}^{+}=\int_{0}^{\infty} u^{l} K^{2}(u) d u$ and $v_{l}^{-}=\int_{-\infty}^{0} u^{l} K^{2}(u) d u$ and define the matrices

$$
V^{+}=\left[\begin{array}{cc}
v_{0}^{+} & v_{1}^{+} \\
v_{1}^{+} & v_{2}^{+}
\end{array}\right], V^{-}=\left[\begin{array}{cc}
v_{0}^{-} & v_{1}^{-} \\
v_{1}^{-} & v_{2}^{-}
\end{array}\right]
$$

and

$$
\Omega^{+}=\left[\begin{array}{cc}
V^{+} & V^{+} \\
V^{+} & V^{+}
\end{array}\right], \Omega^{-}=\left[\begin{array}{cc}
V^{-} & 0 \\
0 & 0
\end{array}\right]
$$

Also define

$$
\Lambda_{l k}^{-}=1\{k=0\} \int_{-\infty}^{0} u^{l+2} K(u) d u
$$

and

$$
\Lambda_{l k}^{+}=\int_{0}^{\infty} u^{l+2} K(u) d u
$$

and let $\Lambda^{-}=\left(\Lambda_{00}^{-}, \Lambda_{10}^{-}, \Lambda_{01}^{-}, \Lambda_{11}^{-}\right)^{\prime}$ and similarly for $\Lambda^{+}=\left(\Lambda_{00}^{+}, \Lambda_{10}^{+}, \Lambda_{01}^{+}, \Lambda_{11}^{+}\right)^{\prime}$ as well as $m^{\prime \prime-}(c)=$ $\left(m_{0}^{\prime \prime-}(c), \ldots, m_{J}^{\prime \prime-}(c)\right)^{\prime}$ and similarly for $m^{\prime \prime+}(c)$. With this notation we can now state the first result.

Theorem 6 Assume that Assumptions 1 4GK: additional reg conditions as in C4 of MF96 are not assumed because of the RD design - double check that this is not causing problems] hold and that $h=$ $O\left(T^{-1 / 5}\right)$. Let $H_{T}=\operatorname{diag}\left(1, h^{-1}, h^{-1}, 1\right)$. Then,

$$
\begin{aligned}
\sqrt{T h}\left(H_{T} \operatorname{vec}\left(\hat{\Pi}^{\prime}-\Pi^{\prime}\right)-\frac{h^{2}}{2}\left(m^{\prime \prime-}\right.\right. & \left.\left.(c) \otimes \Gamma^{-1} \Lambda^{-}+m^{\prime \prime+}(c) \otimes \Gamma^{-1} \Lambda^{+}\right)\right) \\
& \rightarrow_{d} N\left(0, f(c)^{-1}\left(\Sigma^{+}(c) \otimes \Gamma^{-1} \Omega^{+} \Gamma^{\prime-1}+\Sigma^{-}(c) \otimes \Gamma^{-1} \Omega^{-} \Gamma^{\prime-1}\right)\right)
\end{aligned}
$$

as $T \rightarrow \infty$.

It is interesting to note that the product structure of the asymptotic variance covariance matrix is similar to systems estimators with iid errors even though we have not made any such assumptions. The next result considers the marginal limiting distribution of $\hat{\theta}$. Let $b^{+}$be the third element of $\Gamma^{-1} \Lambda^{+}, b^{-}$ the third element of $\Gamma^{-1} \Lambda^{-}, \omega^{+}$the third diagonal element of $\Gamma^{-1} \Omega^{+} \Gamma^{\prime-1}$ and $\omega^{-}$the third diagonal element of $\Gamma^{-1} \Omega^{-} \Gamma^{\prime-1}$.

Theorem 7 Assume that Assumptions 1/4 hold and that $h=O\left(T^{-1 / 5}\right)$. Then,

$$
\sqrt{T h}\left(\hat{\theta}-\theta-\frac{h^{2}}{2}\left(m^{\prime \prime-}(c) b^{-}+m^{\prime \prime+}(c) b^{+}\right)\right) \rightarrow_{d} N\left(0, f(c)^{-1}\left(\Sigma^{-}(c) \omega^{-}+\Sigma^{+}(c) \omega^{+}\right)\right)
$$

as $T \rightarrow \infty$.
Finally, consider the limiting distribution of an individual impulse coefficient $\hat{\theta}_{j}$ for the response at horizon $j$. In this case, let $\sigma_{+j}^{2}(c)$ be the corresponding diagonal element of $\Sigma^{+}(c)$ and $\sigma_{-j}^{2}(c)$ the corresponding diagonal element of $\Sigma^{-}(c)$. We obtain the following result.

Theorem 8 Assume that Assumptions 14 hold and that $h=O\left(T^{-1 / 5}\right)$. Then,

$$
\sqrt{T h}\left(\hat{\theta}_{j}-\theta_{j}-\frac{h^{2}}{2}\left(m_{j}^{\prime \prime-}(c) b^{-}+m_{j}^{\prime \prime+}(c) b^{+}\right)\right) \rightarrow_{d} N\left(0, f(c)^{-1}\left(\sigma_{+j}^{2}(c) \omega^{+}+\sigma_{-j}^{2}(c) \omega^{-}\right)\right)
$$

as $T \rightarrow \infty$.

The results in Theorem 7 and 8 can be used to obtain optimal bandwidth rules analogous to the ones obtained by Masry and Fan (1997) and Imbens and Kalyanaraman (2012). Since we are often interested in joint estimation of the impulse response function $\theta$ it makes sense to consider the average
means squared error across all impulse response coefficients. Let $\lambda \in \mathbb{R}^{J+1}$ with $\|\lambda\|=1$. For example, we consider equal weights $\lambda=1_{J} / J$ where $1_{a}$ is a vector of length $a$ with all elements set equal to one. A second case of interest is $\lambda=e_{j}$ where $e_{j}$ is the $j$-th unit vector in $\mathbb{R}^{J+1}$. Then, $\lambda^{\prime} \hat{\theta}$ is the weighted average of the impulse response coefficients with bias

$$
\frac{h^{2}}{2} \lambda^{\prime}\left(m^{\prime \prime-}(c) b^{-}+m^{\prime \prime+}(c) b^{+}\right)
$$

and variance

$$
\frac{\lambda^{\prime} \Sigma^{-}(c) \lambda \omega^{-}+\lambda^{\prime} \Sigma^{+}(c) \lambda \omega^{+}}{h T f(c)}
$$

The optimal bandwidth is obtained by minimizing the asymptotic mean squared error with respect to $h$ and given as

$$
h_{o p t}=\left(\frac{\lambda^{\prime} \Sigma^{-}(c) \lambda \omega^{-}+\lambda^{\prime} \Sigma^{+}(c) \lambda \omega^{+}}{f(c)\left(\lambda^{\prime}\left(m^{\prime \prime-}(c) b^{-}+m^{\prime \prime+}(c) b^{+}\right)\right)^{2}}\right)^{1 / 5} T^{-1 / 5} .
$$

For a given horizon $j$ this formula specializes to

$$
h_{o p t, j}=\left(\frac{\sigma_{+j}^{2}(c) \omega^{+}+\sigma_{-j}^{2}(c) \omega^{-}}{f(c)\left(m_{j}^{\prime \prime-}(c) b^{-}+m_{j}^{\prime \prime+}(c) b^{+}\right)^{2}}\right)^{1 / 5} T^{-1 / 5}
$$

Note that we are not assuming $b^{-}=-b^{+}$. However, with a symetric kernel it follows that $b^{-}=-b^{+}$and $\omega^{+}=\omega^{-}$. The bandwidth formula the futher simplifies to

$$
h_{o p t, j}=\left(\frac{\omega^{+}}{\left(b^{-}\right)^{2}}\right)^{1 / 5}\left(\frac{\sigma_{+j}^{2}(c)+\sigma_{-j}^{2}(c)}{f(c)\left(m_{j}^{\prime \prime-}(c)-m_{j}^{\prime \prime+}(c)\right)^{2}}\right)^{1 / 5} T^{-1 / 5}
$$

which corresponds to the plug in formula of Imbens and Kalyanaraman (2012). For example, for the Bartlett kernel $K(u)=(1-|u|) 1\{|u| \leq 1\}$ it can be shown that $\omega^{+}=\omega^{-}=24 / 5$ and $b^{-}=-b^{+}=1 / 10$ which leads to $\left(\omega^{+} /\left(b^{-}\right)^{2}\right)^{1 / 5}=2(15)^{1 / 5} \approx 3.4375$ which is the same as the constant obtained in Imbens and Kalyanaraman (2012).

## 3 Proofs

Proof of Theorem 5. The proof of the first part closely follows the argument in HTV. First note that

$$
E\left[y_{t+j} \mid X_{t}=x\right]=E\left[y_{t+j} \mid g\left(\chi_{t}\right)=x\right] .
$$

Using the representation for $y_{t+j}$ one obtains $y_{t+j}=F_{t+j}\left(0, \chi_{t}\right)+\theta_{j}^{D}\left(\chi_{t}\right) D_{t}$

$$
E\left[y_{t+j} \mid g\left(\chi_{t}\right)=x\right]=E\left[F_{t+j}\left(0, \chi_{t}\right)+\theta_{j}^{D}\left(\chi_{t}\right) D_{t}\left(\chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]
$$

Since $D_{t}\left(\chi_{t}\right)=1$ conditional on $g\left(\chi_{t}\right)=x>c$ and $D_{t}\left(\chi_{t}\right)=0$ conditional on $g\left(\chi_{t}\right)=x \leq c$ we obtain for all $x>c$ that

$$
E\left[y_{t+j} \mid g\left(\chi_{t}\right)=x\right]=E\left[F_{t+j}\left(0, \chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]+E\left[\theta_{j}^{D}\left(\chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]
$$

and for all $x \leq c$ that

$$
E\left[y_{t+j} \mid g\left(\chi_{t}\right)=x\right]=E\left[F_{t+j}\left(0, \chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right] .
$$

By Assumption 1 it follows that $\lim _{x \downarrow c} E\left[F_{t+j}\left(0, \chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]=\lim _{x \uparrow c} E\left[F_{t+j}\left(0, \chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]$ and $\lim _{x \downarrow c} E\left[\theta_{j}^{D}\left(\chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]=\lim _{x \uparrow c} E\left[\theta_{j}^{D}\left(\chi_{t}\right) \mid g\left(\chi_{t}\right)=x\right]=E\left[\theta_{j}^{D}\left(\chi_{t}\right) \mid g\left(\chi_{t}\right)=c\right]$. The first result now follows.

For the second part of the Theorem note that $\theta_{j}\left(\varepsilon(\delta), \chi_{t}\right)=F_{t+j}\left(D_{t}\left(\chi_{t}+\varepsilon(\delta)\right), \chi_{t}+\varepsilon(\delta)\right)-$ $F_{t+j}\left(D_{t}\left(\chi_{t}\right), \chi_{t}\right)$ and for $\delta>0$,

$$
\begin{aligned}
E\left[\theta_{j}\left(\varepsilon(\delta), \chi_{t}\right) \mid X_{t}=c\right] & =E\left[F_{t+j}\left(D_{t}\left(\chi_{t}+\varepsilon(\delta)\right), \chi_{t}+\varepsilon(\delta)\right)-F_{t+j}\left(D_{t}\left(\chi_{t}\right), \chi_{t}\right) \mid X_{t}=c\right] \\
& =E\left[F_{t+j}\left(1, \chi_{t}+\varepsilon(\delta)\right) \mid X_{t}=c\right]-E\left[F_{t+j}\left(0, \chi_{t}\right) \mid X_{t}=c\right] .
\end{aligned}
$$

Consider

$$
E\left[F_{t+j}\left(1, \chi_{t}+\varepsilon(\delta)\right) \mid X_{t}=c\right]=E\left[E\left[F_{t+j}(1, \chi) \mid \chi=\chi_{t}+\varepsilon(\delta)\right] \mid X_{t}=c\right] .
$$

By the assumption of continuity, $\lim _{\delta \downarrow 0} E\left[F_{t+j}(1, \chi) \mid \chi=\chi_{t}+\varepsilon(\delta)\right]=E\left[F_{t+j}(1, \chi) \mid \chi=\chi_{t}\right]$ a.s. and $\left|E\left[F_{t+j}(1, \chi) \mid \chi=\chi_{t}+\varepsilon(\delta)\right]\right| \leq B\left(\chi_{t}\right)$ with $E\left[\left|B\left(\chi_{t}\right)\right| \mid X_{t}=c\right]<\infty$. Then it follows from the Lebesque Convergence Theorem (see Royden, 1988, p.91) that

$$
\lim _{\delta \downarrow 0} E\left[F_{t+j}\left(1, \chi_{t}+\varepsilon(\delta)\right) \mid X_{t}=c\right]=E\left[F_{t+j}\left(1, \chi_{t}\right) \mid X_{t}=c\right] \text { a.s. }
$$

and the result follows from the definition of $\theta_{j}^{D}\left(\chi_{t}\right)$.
Proof of Theorem 7. Note that, similar to Masry and Fan (1997, p.168) the estimator vec $\hat{\Pi}$ can be written as

$$
\begin{aligned}
\operatorname{vec}\left(H_{T} \hat{\Pi}^{\prime}\right) & =\left(I \otimes H_{T}\right) \operatorname{vec} \hat{\Pi}^{\prime}=\left(I_{J} \otimes H_{T}\left(Z^{\prime} W Z\right)^{-1} Z^{\prime} W\right) \operatorname{vec} Y \\
& =\left(I_{J} \otimes\left(H_{T} Z^{\prime} W Z H_{T}\right)^{-1} H_{T} Z^{\prime} W\right) \operatorname{vec} Y
\end{aligned}
$$

First consider the matrix

$$
\begin{aligned}
& (T h)^{-1} H_{T} Z^{\prime} W Z H_{T} \\
= & (T h)^{-1} \sum_{t=2}^{T-J}\left[\begin{array}{cccc}
1 & \frac{X_{t}-c}{h} & D_{t} & \frac{X_{t}-c}{h} D_{t} \\
\frac{X_{t}-c}{h} & \left(\frac{X_{t}-c}{h}\right)^{2} & \left(\frac{X_{t}-c}{h}\right) D_{t} & \left(\frac{X_{t}-c}{h}\right)^{2} D_{t} \\
D_{t} & \left(\frac{X_{t}-c}{h}\right) D_{t} & D_{t} & \frac{X_{t}-c}{h} D_{t} \\
\frac{X_{t}-c}{h} D_{t} & \left(\frac{X_{t}-c}{h}\right)^{2} D_{t} & \frac{X_{t}-c}{h} D_{t} & \left(\frac{X_{t}-c}{h}\right)^{2} D_{t}
\end{array}\right] K\left(\frac{X_{t}-c}{h}\right) .
\end{aligned}
$$

Using results from HTV and Masry and Fan (1997, Theorem 1) one finds that

$$
\begin{equation*}
h^{-1} E\left[\left(\frac{X_{t}-c}{h}\right)^{l} K\left(\frac{X_{t}-c}{h}\right)\right]=f(c) \int_{-\infty}^{\infty} u^{l} K(u) d u+o_{h}(1) \text { for } l=0,1,2 . \tag{1}
\end{equation*}
$$

where $o_{h}(1) \rightarrow 0$ as $h \rightarrow 0$. Similarly,

$$
\begin{equation*}
h^{-1} E\left[D_{t}\left(\frac{X_{t}-c}{h}\right)^{l} K\left(\frac{X_{t}-c}{h}\right)\right]=f(c) \int_{0}^{\infty} u^{l} K(u) d u+o_{h}(1) \text { for } l=0,1,2 \tag{2}
\end{equation*}
$$

Let $\mu_{l k}=\int_{-\infty}^{\infty} 1\{u>0\}^{k} u^{l} K(u) d u$, which implies that for $h \rightarrow 0$ such that $h T \rightarrow \infty$ that

$$
(T h)^{-1} E\left[H_{T} Z^{\prime} W Z H_{T}\right]=f(c) \Gamma .
$$

It follows from Masry and Fan (1997, Theorem 1) that

$$
\begin{equation*}
\operatorname{Th} \operatorname{Var}\left[(T h)^{-1} \sum_{t=1}^{T-J}\left(\frac{X_{t}-c}{h}\right)^{l} K\left(\frac{X_{t}-c}{h}\right)\right] \rightarrow f(c) \vartheta_{2 l} \text { for } l=0,1,2 \tag{3}
\end{equation*}
$$

where $\vartheta_{l}=\int_{-\infty}^{\infty} u^{l} K^{2}(u) d u$. For

$$
\xi_{t}^{l}=D_{t}\left(\frac{X_{t}-c}{h}\right)^{l} K\left(\frac{X_{t}-c}{h}\right)
$$

it remains to consider

$$
\begin{equation*}
T h \operatorname{Var}\left[(T h)^{-1} \sum_{t=1}^{T-J} \xi_{t}^{l}\right]=(T h)^{-1} \sum_{t=1}^{T-J} \operatorname{Var}\left(\xi_{t}^{l}\right)+2 h^{-1} \sum_{j=1}^{T-J}\left(1-\frac{j}{T}\right) \operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right) \tag{4}
\end{equation*}
$$

where by (2) it follows that

$$
\begin{align*}
h^{-1} \operatorname{Var}\left(\xi_{t}^{l}\right)= & h^{-1} E\left[D_{t}\left(\frac{X_{t}-c}{h}\right)^{2 l} K^{2}\left(\frac{X_{t}-c}{h}\right)\right]  \tag{5}\\
& -h\left(E\left[h^{-1} D_{t}\left(\frac{X_{t}-c}{h}\right)^{l} K\left(\frac{X_{t}-c}{h}\right)\right]\right)^{2} \\
= & h^{-1} E\left[D_{t}\left(\frac{X_{t}-c}{h}\right)^{2 l} K^{2}\left(\frac{X_{t}-c}{h}\right)\right]+o_{h}(1) \\
= & f(c) \int_{0}^{\infty} u^{2 l} K^{2}(u) d u+o_{h}(1) .
\end{align*}
$$

For the covariance term in (4) follow Masry and Fan (1997) and choose $d_{T}$ such that $d_{T} \rightarrow \infty$ and $d_{T} h \rightarrow 0$. Then,

$$
\begin{equation*}
h^{-1} \sum_{j=1}^{T-J}\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right|=h^{-1} \sum_{j=1}^{d_{T}}\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right|+h^{-1} \sum_{j=d_{T}+1}^{T-J}\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right| \tag{6}
\end{equation*}
$$

where

$$
\begin{aligned}
& h^{-2}\left|E\left[\xi_{1}^{l} \xi_{1+j}^{l}\right]\right| \\
= & h^{-2}\left|\int_{-\infty}^{\infty} 1\{v>c\} 1\{u>c\}\left(\frac{v-c}{h}\right)^{l}\left(\frac{u-c}{h}\right)^{l} K\left(\frac{v-c}{h}\right) K\left(\frac{u-c}{h}\right) f_{j}(u, v) d u d v\right|
\end{aligned}
$$

and therefore

$$
\begin{aligned}
& h^{-2}\left|E\left[D_{1} D_{j}\left(\frac{X_{0}-c}{h}\right)^{l}\left(\frac{X_{j}-c}{h}\right)^{l} K\left(\frac{X_{0}-c}{h}\right) K\left(\frac{X_{j}-c}{h}\right)\right]\right| \\
\leq & h^{-2} \int_{-\infty}^{\infty}\left|\left(\frac{v-c}{h}\right)^{l}\left(\frac{u-c}{h}\right)^{l} K\left(\frac{v-c}{h}\right) K\left(\frac{u-c}{h}\right)\right|\left|f_{j}(u, v)-f(u) f(v)\right| d u d v \\
& +\left|\int_{-\infty}^{\infty} 1\{v>c\}\left(\frac{v-c}{h}\right)^{l} h^{-1} K\left(\frac{v-c}{h}\right) f(v) d v\right|^{2} \\
\leq & M\left(\int_{-\infty}^{\infty}\left|\left(\frac{v-c}{h}\right)^{l} h^{-1} K\left(\frac{v-c}{h}\right)\right| d v\right)^{2}+\left|f(c) \int_{0}^{\infty} u^{l} K(u) d u+o_{h}(1)\right|^{2}
\end{aligned}
$$

where the first inequality follows from Assumption 2 (ii) and the second inequality follows from (2). By
a change of variables we have

$$
\int_{-\infty}^{\infty}\left|\left(\frac{v-c}{h}\right)^{l} h^{-1} K\left(\frac{v-c}{h}\right)\right| d v=\int_{-\infty}^{\infty}\left|u^{l} K(u)\right| d v=\int_{0}^{\infty} u^{l} K(u) d v+\int_{0}^{\infty} u^{l} K(-u) d v \leq M
$$

by Assumption 2 (iv). Also note

$$
\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right| \leq\left|E\left[\xi_{1}^{l} \xi_{1+j}^{l}\right]\right|+\left|E\left[\xi_{1}^{l}\right]\right|\left|E\left[\xi_{1+j}^{l}\right]\right|
$$

where

$$
h^{-2}\left|E\left[\xi_{1}^{l}\right]\right|\left|E\left[\xi_{1+j}^{l}\right]\right|=\left(f(c) \int_{0}^{\infty} u^{l} K(u) d u\right)^{2}+o_{h}(1)
$$

by (2). This implies that

$$
\begin{equation*}
h^{-1} \sum_{j=1}^{d_{T}}\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right| \leq h d_{T} M=o(1) . \tag{7}
\end{equation*}
$$

For the second term in (6) use the mixing inequality in Hall and Heyde (1980, Corollary A2), also given in Masry and Fan (1997, p.171) whereby

$$
\begin{equation*}
h^{-2}\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right| \leq 8 \alpha_{j}^{1-2 / \delta} E\left[\left|h^{-1} \xi_{1}^{l}\right|^{\delta}\right]^{2 / \delta} \tag{8}
\end{equation*}
$$

Since

$$
\begin{align*}
E\left[\left|h^{-1} \xi_{1}^{l}\right|^{\delta}\right] & =E\left[\left|D_{1}\left(\frac{X_{0}-c}{h}\right)^{l} h^{-1} K\left(\frac{X_{0}-c}{h}\right)\right|^{\delta}\right]  \tag{9}\\
& =\int_{-\infty}^{\infty} 1(u>c)\left|\left(\frac{u-c}{h}\right)^{l} h^{-1} K\left(\frac{u-c}{h}\right)\right|^{\delta} f(u) d u \\
& \leq \sup _{u} f(u) \int_{-\infty}^{\infty} h^{-\delta}\left|\left(\frac{u-c}{h}\right)^{l} K\left(\frac{u-c}{h}\right)\right|^{\delta} d u \\
& =\sup _{u} f(u) h^{-\delta+1} \int_{-\infty}^{\infty}\left|u^{l} K(u)\right|^{\delta} d u \\
& \leq \sup _{u} f(u) \sup _{u} K(u)^{\delta-1} h^{-\delta+1} \int_{-\infty}^{\infty}|u|^{\delta l} K(u) d u \\
& \leq M h^{-\delta+1}
\end{align*}
$$

where the first inequality follows from Assumption 2 (i), the second inequality follows from Assumption 2 (iv) and the last inequality similarly follows from Assumption 2 (iv). Substituting (9) in (8) leads to,
using the same argument as in Mazry and Fan (1997, p.172), i.e. taking $h^{1-2 / \delta} d_{t}^{a}=1$ such that $h d_{t}^{\alpha} \rightarrow 0$ holds,

$$
\begin{align*}
h^{-1} \sum_{j=d_{T}+1}^{T-J}\left|\operatorname{Cov}\left(\xi_{1}^{l}, \xi_{1+j}^{l}\right)\right| & \leq h 8 M^{2 / \delta} h^{-2+2 / \delta} \sum_{j=d_{T}+1}^{T-J} \alpha_{j}^{1-2 / \delta}  \tag{10}\\
& \leq 8 M^{2 / \delta} h^{-1+2 / \delta} d_{t}^{-a} \sum_{j=d_{T}+1}^{T-J} l^{a} \alpha_{j}^{1-2 / \delta}=o(1) .
\end{align*}
$$

Together, (6), (7) and (10) implies that

$$
\begin{equation*}
T h \operatorname{Var}\left[(T h)^{-1} \sum_{t=2}^{T-J} \xi_{t}^{l}\right]=f(c) \int_{0}^{\infty} u^{l} K^{2}(u) d u+o_{h}(1) . \tag{11}
\end{equation*}
$$

By (3) and (11) it follows that

$$
(T h)^{-1} H_{T} Z^{\prime} W Z H_{T} \rightarrow_{p} \Gamma
$$

and that

$$
\begin{aligned}
\sqrt{T h} \operatorname{vec}\left(H_{T}\left(\hat{\Pi}^{\prime}-\Pi^{\prime}\right)\right) & =\left(I_{J} \otimes T h\left(H_{T} Z^{\prime} W Z H_{T}\right)^{-1}(T h)^{-1 / 2} H_{T} Z^{\prime} W\right) \operatorname{vec}\left(Y-Z \Pi^{\prime}\right) \\
& =\left(I_{J} \otimes(f(c) \Gamma)^{-1}\right)\left(I_{J} \otimes(T h)^{-1 / 2} H_{T} Z^{\prime} W\right) \operatorname{vec}\left(Y-Z \Pi^{\prime}\right)+o_{p}(1)
\end{aligned}
$$

The term $\left(I_{J} \otimes T^{-1 / 2} H_{T} Z^{\prime} W\right)$ vec $Y$ is analyzed next. Note that

$$
\left(I \otimes(T h)^{-1 / 2} H_{T} Z^{\prime} W\right) \operatorname{vec}\left(Y-Z \Pi^{\prime}\right)=(T h)^{-1 / 2} \sum_{t=1}^{T-J}\left[\begin{array}{c}
H_{T} Z_{t}\left(y_{t}-Z_{t}^{\prime} \pi_{0}\right) K\left(\frac{X_{t}-c}{h}\right) \\
\vdots \\
H_{T} Z_{t}\left(y_{t+J}-Z_{t}^{\prime} \pi_{J}\right) K\left(\frac{X_{t}-c}{h}\right)
\end{array}\right]
$$

where $\pi_{j}$ is the $j$-th column of $\Pi^{\prime}$. As in HTV and Assumption 4 let $m_{j}(x)=E\left[y_{t+j} \mid X_{t}=x\right], m_{j}^{+}\left(x_{0}\right)=$ $\lim _{x \rightarrow x_{0}^{+}} E\left[y_{t+j} \mid X_{t}=x\right]$ and $m_{j}^{-}\left(x_{0}\right)=\lim _{x \rightarrow x_{0}^{-}} E\left[y_{t+j} \mid X_{t}=x\right]$. It follows that $E\left(y_{t+j} \mid X_{t}\right)=m_{j}^{-}\left(X_{t}\right)\left(1-D_{t}\right)+$ $m_{j}^{+}\left(X_{t}\right) D_{t}=m_{j}^{-}\left(X_{t}\right)+\left(m_{j}^{+}\left(X_{t}\right)-m_{j}^{-}\left(X_{t}\right)\right) D_{t}$. This implies that

$$
E\left[y_{t+j} \mid X_{t}\right]-Z_{t}^{\prime} \pi_{0}=m_{j}^{-}\left(X_{t}\right)-a_{j}-b_{j}\left(X_{t}-c\right)+\left(m_{j}^{+}\left(X_{t}\right)-m_{j}^{-}\left(X_{t}\right)-\theta_{j}-\gamma_{j}\left(X_{t}-c\right)\right) D_{t} .
$$

Following HTV, define

$$
\begin{aligned}
\zeta_{j}(x)= & m_{j}^{-}(x)-a_{j}-b_{j}(x-c)+\left(m_{j}^{+}(x)-m_{j}^{-}(x)-\theta_{j}-\gamma_{j}(x-c)\right) 1(x>c) \\
& -1 / 2 m^{\prime \prime-}(x-c)^{2}-1 / 2\left(m_{j}^{\prime \prime+}(x)-m_{j}^{\prime \prime-}(x)\right)(x-c)^{2} 1(x>c)
\end{aligned}
$$

It follows that

$$
\begin{aligned}
E\left[y_{t}-z_{t} \pi_{0}\right] & =E\left[E\left[y_{t+j} \mid X_{t}\right]-z_{t} \pi_{0}\right] \\
& =E\left[\left(m_{j}^{-}\left(X_{t}\right)+\left(m_{j}^{+}\left(X_{t}\right)-m_{j}^{-}\left(X_{t}\right)\right) D_{t}-z_{t} \pi_{0}\right)\right] \\
& =E\left[1 / 2\left(m^{\prime \prime-}(x-c)^{2}+\left(m_{j}^{\prime \prime+}(x)-m_{j}^{\prime \prime-}(x)\right)\right)(x-c)^{2} 1(x>c)+\zeta_{j}(x)\right]
\end{aligned}
$$

where $\sup _{x \in[c-h, c+h]}\left|\zeta_{j}(x)\right|=o\left(h^{2}\right)$. We then have

$$
\begin{aligned}
& E\left[(T h)^{-1} \sum_{t=2 T}^{T-J} H_{T} Z_{t}\left(y_{t}-z_{t} \pi_{0}\right) K\left(\frac{X_{t}-c}{h}\right)\right] \\
= & \frac{1}{2} E\left[(T h)^{-1} \sum_{t=2 T}^{T-J} H_{T} Z_{t} m^{\prime \prime-}\left(X_{t}\right)\left(X_{t}-c\right)^{2} K\left(\frac{X_{t}-c}{h}\right)\right] \\
& +\frac{1}{2} E\left[(T h)^{-1} \sum_{t=2 T}^{T-J} H_{T} Z_{t}\left(\left(m_{j}^{\prime \prime+}\left(X_{t}\right)-m_{j}^{\prime \prime-}\left(X_{t}\right)\right) 1\left(X_{t}>c\right)\right)\left(X_{t}-c\right)^{2} K\left(\frac{X_{t}-c}{h}\right)\right] \\
& +\frac{1}{2} E\left[(T h)^{-1} \sum_{t=2 T}^{T-J} H_{T} Z_{t} \zeta_{j}(x) K\left(\frac{X_{t}-c}{h}\right)\right]
\end{aligned}
$$

where the elements in $H_{T} Z_{t}$ are $\left(\left(X_{t}-c\right) / h\right)^{l} D_{t}^{k}$ for $k, l \in\{0,1\}$. It follows by similar arguments as in HTV that

$$
\begin{aligned}
& h^{-1} E\left[\left(\frac{X_{t}-c}{h}\right)^{l} D_{t}^{k}\left\{1 / 2 m^{\prime \prime-}\left(X_{t}\right)+1 / 2\left(m_{j}^{\prime \prime+}\left(X_{t}\right)-m_{j}^{\prime \prime-}\left(X_{t}\right)\right) 1\left(X_{t}>c\right)\right\}\left(X_{t}-c\right)^{2} K\left(\frac{X_{t}-c}{h}\right)\right] \\
= & 1 / 2\left(m_{j}^{\prime \prime-}(c) \Lambda_{l k}^{-}+m_{j}^{\prime \prime+}(c) \Lambda_{l k}^{+}\right) f(c) h^{2}+o_{h}\left(h^{2}\right) .
\end{aligned}
$$

For example, by a change of variables, one obtains

$$
\begin{aligned}
& h^{-1} E\left[\left(\frac{X_{t}-c}{h}\right)^{l} D_{t}^{k} m^{\prime \prime-}\left(X_{t}\right)\left(1-1\left(X_{t}>c\right)\right)\left(X_{t}-c\right)^{2} K\left(\frac{X_{t}-c}{h}\right)\right] \\
= & h^{2} \int u^{2+l} m^{\prime \prime-}(u h+c) 1(u h>0)^{k} 1(u h \leq 0) K(u) f(u h+c) d u \\
= & h^{2} m^{\prime \prime-}(c) f(c) 1\{k=0\} \int_{-\infty}^{0} u^{2+l} K(u) d u+o_{h}\left(h^{2}\right)=m_{j}^{\prime \prime-}(c) f(c) \Lambda_{l k}^{-} h^{2}+o\left(h^{2}\right) .
\end{aligned}
$$

Similarly,

$$
\begin{aligned}
& h^{-1} E\left[\left(\frac{X_{t}-c}{h}\right)^{l} D_{t}^{k} m^{\prime \prime+}\left(X_{t}\right) 1\left(X_{t}>c\right)\left(X_{t}-c\right)^{2} K\left(\frac{X_{t}-c}{h}\right)\right] \\
= & h^{2} \int u^{2+l} m^{\prime \prime+}(u h+c) 1(u h>0) K(u) f(u h+c) d u \\
= & h^{2} m^{\prime \prime+}(c) f(c) \int_{0}^{\infty} u^{2+l} K(u) d u+o_{h}\left(h^{2}\right)=m_{j}^{\prime \prime+}(c) f(c) \Lambda_{l k}^{+} h^{2}+o\left(h^{2}\right) .
\end{aligned}
$$

The asymptotic bias of the score can now be written as

$$
E\left[(T h)^{-1} \sum_{t=2 T}^{T-J} H_{T} Z_{t}\left(y_{t+j}-z_{t} \pi_{0}\right) K\left(\frac{X_{t}-c}{h}\right)\right]=\frac{1}{2}\left(m_{j}^{\prime \prime-}(c) \Lambda^{-}+m_{j}^{\prime \prime+}(c) \Lambda^{+}\right) f(c) h^{2}+o_{h}\left(h^{2}\right) .
$$

Furthermore,

$$
E\left[\left(I \otimes(T h)^{-1} H_{T} Z^{\prime} W\right) \operatorname{vec}\left(Y-Z \Pi^{\prime}\right)\right]=\frac{1}{2}\left(m^{\prime \prime-}(c) \otimes \Lambda^{-}+m^{\prime \prime+}(c) \otimes \Lambda^{+}\right) f(c) h^{2}+o_{h}\left(h^{2}\right)
$$

where $m^{\prime \prime-}(c)=\left(m_{0}^{\prime \prime-}(c), \ldots ., m_{J}^{\prime \prime-}(c)\right)^{\prime}$ and similarly for $m^{\prime \prime+}(c)$.
Let $m_{j}(x)=E\left[y_{t+J} \mid X_{t}=x\right]$. Next consider, as Masry and Fan (1997, p. 169),

$$
Q_{T}=(T h)^{-1 / 2} \sum_{t=1}^{T-J}\left[\begin{array}{c}
H_{T} Z_{t}\left(y_{t}-m_{0}\left(X_{t}\right)\right) K\left(\frac{X_{t}-c}{h}\right) \\
\vdots \\
H_{T} Z_{t}\left(y_{t+J}-m_{J}\left(X_{t}\right)\right) K\left(\frac{X_{t-c}}{h}\right)
\end{array}\right]
$$

where the sum is over typical elements of the form

$$
\xi_{t, l k}^{j}=\left(\frac{X_{t}-c}{h}\right)^{l} D_{t}^{k}\left(y_{t+j}-m_{j}\left(X_{t}\right)\right) h^{-1} K\left(\frac{X_{t}-c}{h}\right) \text { for } l, k \in\{0,1\}
$$

Fix a vector $\lambda \in \mathbb{R}^{4 J+4}$ with $\|\lambda\|=1$. Then,

$$
\lambda^{\prime} Q_{T}=(T / h)^{-1 / 2} \sum_{t=1}^{T-J} \sum_{j=0}^{J} \sum_{l, k=0}^{1} \lambda_{l k}^{j} \xi_{t, l k}^{j} \equiv(T / h)^{-1 / 2} \sum_{t=1}^{T-J} \xi_{t}
$$

where $\xi_{t}=\sum_{j=0}^{J} \sum_{l, k=0}^{1} \lambda_{l k}^{j} \xi_{t, l k}^{j}$. Let $\lambda_{l k}=\left(\lambda_{l k}^{0}, \ldots, \lambda_{l k}^{J}\right), \lambda^{j}=\left(\lambda_{00}^{j}, \lambda_{10}^{j}, \lambda_{01}^{j}, \lambda_{11}^{j}\right)^{\prime}, \lambda=\left(\lambda^{0^{\prime}}, \ldots, \lambda^{J^{\prime}}\right)^{\prime}$ and $m\left(X_{t}\right)=\left(m_{0}\left(X_{t}\right), \ldots, m_{J}\left(X_{t}\right)\right)^{\prime}$. First consider

$$
\begin{aligned}
h \operatorname{Var}\left(\xi_{t}\right) & =h \operatorname{Var}\left(\sum_{l, k=0}^{1} \lambda_{l k}^{\prime}\left(Y_{t}-m\left(X_{t}\right)\right)\left(\frac{X_{t}-c}{h}\right)^{l} D_{t}^{k} h^{-1} K\left(\frac{X_{t}-c}{h}\right)\right) \\
& =h \operatorname{Var}\left(\sum_{l=0}^{1}\left(\frac{X_{t}-c}{h}\right)^{l} h^{-1} K\left(\frac{X_{t}-c}{h}\right)\left(\lambda_{l 0}^{\prime}\left(Y_{t}-m\left(X_{t}\right)\right)\left(1-D_{t}\right)+\left(\lambda_{l 0}+\lambda_{l 1}\right)^{\prime}\left(Y_{t}-m\left(X_{t}\right)\right) D_{t}\right)\right)
\end{aligned}
$$

and noting that the two components associated with $\left(1-D_{t}\right)$ and $D_{t}$ are orthogonal leads to

$$
\begin{aligned}
h \operatorname{Var}\left(\xi_{t}\right)= & \sum_{l_{1}, l_{2}=0}^{1} E\left[\left(\lambda_{l_{1} 0}^{\prime} \Sigma\left(X_{t}\right) \lambda_{l_{2} 0}\left(1-D_{t}\right)\right)\left(\frac{X_{t}-c}{h}\right)^{l_{1}+l_{2}} h^{-1} K^{2}\left(\frac{X_{t}-c}{h}\right)\right] \\
& +\sum_{l_{1}, l_{2}=0}^{1} E\left[\left(\lambda_{l_{1} 0}+\lambda_{l_{1} 1}\right)^{\prime} \Sigma\left(X_{t}\right)\left(\lambda_{l_{2} 0}+\lambda_{l_{2} 1}\right) D_{t}\left(\frac{X_{t}-c}{h}\right)^{l_{1}+l_{2}} h^{-1} K^{2}\left(\frac{X_{t}-c}{h}\right)\right] \\
= & f(c) \sum_{l_{1}, l_{2}=0}^{1}\left(\lambda_{l_{1} 0}^{\prime} \Sigma^{-}(c) \lambda_{l_{2} 0} \int_{-\infty}^{0} u^{l_{1}+l_{2}} K^{2}(u) d u\right) \\
& +f(c) \sum_{l_{1}, l_{2}=0}^{1}\left(\lambda_{l_{1} 0}+\lambda_{l_{1} 1}\right)^{\prime} \Sigma^{+}(c)\left(\lambda_{l_{2} 0}+\lambda_{l_{2} 1}\right) \int_{0}^{\infty} u^{l_{1}+l_{2}} K^{2}(u) d u+o_{h}(1) .
\end{aligned}
$$

It also follows by the same arguments as in (7) and (10) that

$$
h \sum_{j=1}^{T-J}\left|\operatorname{Cov}\left(\xi_{1}, \xi_{1+j}\right)\right|=o(1)
$$

It then follows

$$
T h \operatorname{Var}\left(\lambda^{\prime} Q_{T}\right) \rightarrow f(c) \sum_{l_{1}, l_{2}=0}^{1}\left(\lambda_{l_{1} 0}^{\prime} \Sigma^{-}(c) \lambda_{l_{2} 0} v_{l_{1}+l_{2}}^{-}+\left(\lambda_{l_{1} 0}+\lambda_{l_{1} 1}\right)^{\prime} \Sigma^{+}(c)\left(\lambda_{l_{2} 0}+\lambda_{l_{2} 1}\right) v_{l_{1}+l_{2}}^{+}\right) .
$$

By uusing the definitions of $\Omega^{-}$and $\Omega^{+}$the result can be expressed in matrix form as

$$
T h \operatorname{Var}\left(Q_{T}\right) \rightarrow f(c)\left(\Sigma^{+}(c) \otimes \Omega^{+}+\Sigma^{-}(c) \otimes \Omega^{-}\right)
$$

By the same arguments as in the proof of Theorem 3 of Masry and Fan (1997) it can be shown that

$$
\sqrt{T h}\left(\lambda^{\prime} Q_{T}\right) \rightarrow_{d} N\left(0, f(c) \lambda^{\prime}\left(\Sigma^{+}(c) \otimes \Omega^{+}+\Sigma^{-}(c) \otimes \Omega^{-}\right) \lambda\right)
$$

which in turn implies by the Cramer-Wold theorem and the continuous mapping theorem that

$$
\sqrt{T h}\left(\left(I \otimes f(c)^{-1} \Gamma^{-1}\right) Q_{T}\right) \rightarrow_{d} N\left(0, f(c)^{-1}\left(\Sigma^{+}(c) \otimes \Omega^{+}+\Sigma^{-}(c) \otimes \Omega^{-}\right)\right) .
$$

Finally, deduce that

$$
\begin{aligned}
\sqrt{T h}\left(H_{T} \operatorname{vec}\left(\hat{\Pi}^{\prime}-\Pi^{\prime}\right)-\frac{1}{2}\left(m^{\prime \prime-}(c) \otimes \Lambda^{-}+m^{\prime \prime+}\right.\right. & \left.\left.(c) \otimes \Lambda^{+}\right) f(c)\right) \\
& \rightarrow_{d} N\left(0, f(c)^{-1}\left(\Sigma^{+}(c) \otimes \Omega^{+}+\Sigma^{-}(c) \otimes \Omega^{-}\right)\right)
\end{aligned}
$$

Proof of Theorem 7. The result follows directly from Theorem 7, the fact that $\Pi=(a, b, \theta, \gamma)$ and that the limting distribution in Theorem 7 is for the parameter vector vec $\left(\Pi^{\prime}\right)$.

Proof of Theorem 8. The result follows directly from Theorem 7 .

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## APPENDIX FIGURES

Figure A-1: Effects on Domestic Interest Rates


The dependent variable is the interbank interest rate, Colombia's analogue of the federal funds rate in the US, relative to its level at the time of the auction. The solid curve presents a series of regression discontinuity estimates implemented using local linear regression of the dependent variable on the running variable using daily data. Dashed curves display $95 \%$ confidence intervals of the estimates.

Figure A-2: 60 day IRFs of Sterilization Mechanisms


Panes (a) and (b) show the effects of repurchasing agreements, while Panes (c) and (d) show the effects of domestic sovereign bonds. All variables measured in billion ( $10^{9}$ ) pesos.

Figure A-3: 60 Day Exchange Rate Response


The dependent variable is the log daily average spot rate relative to the log average spot rate the day before the auction. The solid curve presents a series of regression discontinuity estimates implemented using local linear regression on daily data. Dashed curves display $95 \%$ confidence intervals of the estimates. We define the time CIP holds as July 1, 2003 to June 30, 2008 and the time CIP does not hold as all dates before and after this time period.

Figure A-4: Ratio of Dollars-Denominated to Peso-Denominated Assets, Top Five Banks, All But Forwards


The dependent variable is the ratio of net dollar denominated assets to peso-denominated government bonds held by Colombia's 5 largest banks, relative to its value at the time of the auction. This variable does not include derivatives, i.e. forward contracts. The solid curve presents a series of regression discontinuity estimates implemented using local linear regression on daily data. Dashed curves display $95 \%$ confidence intervals of the estimates.

Figure A-5: Ratio of Dollars-Denominated to Peso-Denominated Assets, Top Five Banks, Including Forwards


The dependent variable is the ratio of net dollar denominated assets to peso-denominated government bonds held by Colombia's 5 largest banks, relative to its value at the time of the auction. This variable includes derivatives, i.e. forward contracts. The solid curve presents a series of regression discontinuity estimates implemented using local linear regression on daily data. Dashed curves display $95 \%$ confidence intervals of the estimates.

Figure A-6: Effects on Net Capital Flows - Domestic Investors


The dependent variable is the net capital inflows by domestic investors in the form of loans since the auction, in millions of dollars. The solid curve presents a series of regression discontinuity estimates implemented using local linear regression on daily data. Dashed curves display $95 \%$ confidence intervals of the estimates. We define the time CIP holds as July 1, 2003 to June 30, 2008 and the time CIP does not hold as all dates before and after this time period.

Figure A-7: Effects on Net Capital Flows - Foreign Investors


The dependent variable is cumulative capital inflows by foreign investors in the form of loans since the auction, in millions of dollars. The solid curve presents a series of regression discontinuity estimates implemented using local linear regression on daily data. Dashed curves display $95 \%$ confidence intervals of the estimates. We define the time CIP holds as July 1, 2003 to June 30, 2008 and the time CIP does not hold as all dates before and after this time period.



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